

☐ 2 / 2

Patent Number:

JP61094829 A

19860513

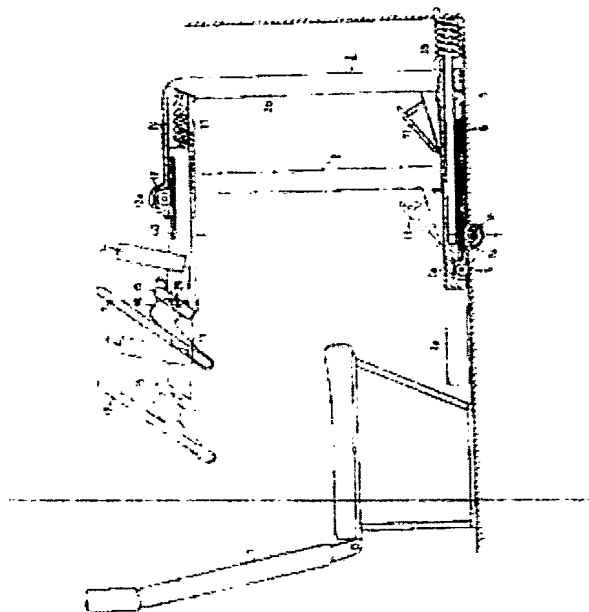
AUTOMOBILE

(JP61094829)

PURPOSE: To ensure an optimum control position, by a method wherein a pedalling type control body for running control is located to a control stand the position of which is longitudinally controllable, and a manual type control body for running control is located so that its position is adjustable independently from the pedalling type control body for running control.

CONSTITUTION: A distance between a driver seat 1 and a control stand 2 is decreased by forward-running a geared motor 7 through control of a switch. In which case, through engagement of a driving gear 7a with a rack 6, the control stage 2 is guided by a guide rod 9 and is moved backward. This causes a brake pedal and accel pedal 11 to be located to an optimum control position. Further, in order to set the control position of a handle 17 to an optimum spot, a geared motor 12 is run through control of a second switch. This causes a mounting body 13 to be moved in a manner to be guided by a guide hole 2c.

COPYRIGHT: (C)1986,JPO&Japio




©Questel Orbit

Inventor(s): ITO MINORU
NUMAZAWA MITSUO

Patent Assignee: TOYODA
AUTOMATIC LOOM
WORKS

Orig. Patent Assignee: (A) TOYODA AUTOM
LOOM WORKS LTD

FamPat family

 JP61094829	A	19860513 [JP61094829] Doc. Laid open to publ. Inspec. 1984JP-0215534 19841015
STG:		
AP :		

Priority Details: 1984JP-0215534
19841015

©QUESTEL-ORBIT

BEST AVAILABLE COPY